

NAG Fortran Library Routine Document

G02DAF

Note: before using this routine, please read the Users' Note for your implementation to check the interpretation of *bold italicised* terms and other implementation-dependent details.

1 Purpose

G02DAF performs a general multiple linear regression when the independent variables may be linearly dependent. Parameter estimates, standard errors, residuals and influence statistics are computed. G02DAF may be used to perform a weighted regression.

2 Specification

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SUBROUTINE G02DAF(MEAN, WEIGHT, N, X, LDX, M, ISX, IP, Y, WT, RSS, IDF,
1          B, SE, COV, RES, H, Q, LDQ, SVD, IRANK, P, TOL, WK,
2          IFAIL)
  INTEGER      N, LDX, M, ISX(M), IP, IDF, LDQ, IRANK, IFAIL
  real       X(LDX,M), Y(N), WT(*), RSS, B(IP), SE(IP),
1          COV(IP*(IP+1)/2), RES(N), H(N), Q(LDQ,IP+1),
2          P(2*IP+IP*IP), TOL, WK(5*(IP-1)+IP*IP)
  LOGICAL     SVD
  CHARACTER*1 MEAN, WEIGHT

```

3 Description

The general linear regression model is defined by

$$y = X\beta + \epsilon,$$

where y is a vector of n observations on the dependent variable,

X is a n by p matrix of the independent variables of column rank k ,

β is a vector of length p of unknown parameters,

and ϵ is a vector of length n of unknown random errors such that $\text{var } \epsilon = V\sigma^2$, where V is a known diagonal matrix.

If $V = I$, the identity matrix, then least-squares estimation is used. If $V \neq I$, then for a given weight matrix $W \propto V^{-1}$, weighted least-squares estimation is used.

The least-squares estimates $\hat{\beta}$ of the parameters β minimize $(y - X\beta)^T(y - X\beta)$ while the weighted least-squares estimates minimize $(y - X\beta)^T W(y - X\beta)$.

G02DAF finds a QR decomposition of X (or $W^{1/2}X$ in weighted case), i.e.,

$$X = QR^* \quad (\text{or } W^{1/2}X = QR^*),$$

where $R^* = \begin{pmatrix} R \\ 0 \end{pmatrix}$ and R is a p by p upper triangular matrix and Q is an n by n orthogonal matrix. If R is of full rank, then $\hat{\beta}$ is the solution to

$$R\hat{\beta} = c_1,$$

where $c = Q^T y$ (or $Q^T W^{1/2} y$) and c_1 is the first p elements of c . If R is not of full rank a solution is obtained by means of a singular value decomposition (SVD) of R ,

$$R = Q_* \begin{pmatrix} D & 0 \\ 0 & 0 \end{pmatrix} P^T,$$

where D is a k by k diagonal matrix with non-zero diagonal elements, k being the rank of R , and Q_* and P are p by p orthogonal matrices. This gives the solution

$$\hat{\beta} = P_1 D^{-1} Q_{*1}^T c_1,$$

P_1 being the first k columns of P , i.e., $P = (P_1 P_0)$, and Q_{*1} being the first k columns of Q_* .

Details of the SVD, are made available, in the form of the matrix P^* :

$$P^* = \begin{pmatrix} D^{-1} P_1^T \\ P_0^T \end{pmatrix}.$$

This will be only one of the possible solutions. Other estimates may be obtained by applying constraints to the parameters. These solutions can be obtained by using G02DKF after using G02DAF. Only certain linear combinations of the parameters will have unique estimates; these are known as estimable functions.

The fit of the model can be examined by considering the residuals, $r_i = y_i - \hat{y}_i$, where $\hat{y}_i = X_i \hat{\beta}$ are the fitted values. The fitted values can be written as Hy for an n by n matrix H . The i th diagonal elements of H , h_i , give a measure of the influence of the i th values of the independent variables on the fitted regression model. The values h_i are sometimes known as leverages. Both r_i and h_i are provided by G02DAF.

The output of G02DAF also includes $\hat{\beta}$, the residual sum of squares and associated degrees of freedom, $(n - k)$, the standard errors of the parameter estimates and the variance-covariance matrix of the parameter estimates.

In many linear regression models the first term is taken as a mean term or an intercept, i.e., $X_{i,1} = 1$, for $i = 1, 2, \dots, n$. This is provided as an option. Also only some of the possible independent variables are required to be included in a model, a facility to select variables to be included in the model is provided.

Details of the QR decomposition and, if used, the SVD, are made available. These allow the regression to be updated by adding or deleting an observation using G02DCF, adding or deleting a variable using G02DEF and G02DFE or estimating and testing an estimable function using G02DNF.

4 References

- Cook R D and Weisberg S (1982) *Residuals and Influence in Regression* Chapman and Hall
- Draper N R and Smith H (1985) *Applied Regression Analysis* (2nd Edition) Wiley
- Golub G H and van Loan C F (1996) *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore
- Hammarling S (1985) The singular value decomposition in multivariate statistics *SIGNUM Newsl.* **20** (3) 2–25
- McCullagh P and Nelder J A (1983) *Generalized Linear Models* Chapman and Hall
- Searle S R (1971) *Linear Models* Wiley

5 Parameters

- 1: MEAN – CHARACTER*1 *Input*
On entry: indicates if a mean term is to be included.
 If MEAN = 'M' (Mean), a mean term, intercept, will be included in the model.
 If MEAN = 'Z' (Zero), the model will pass through the origin, zero-point.
Constraint: MEAN = 'M' or 'Z'.
- 2: WEIGHT – CHARACTER*1 *Input*
On entry: indicates if weights are to be used.
 If WEIGHT = 'U' (Unweighted), least-squares estimation is used.

If WEIGHT = 'W' (Weighted), weighted least-squares is used and weights must be supplied in WT.

Constraint: WEIGHT = 'U' or 'W'.

- 3: N – INTEGER *Input*
On entry: the number of observations, n .
Constraint: $N \geq 2$.
- 4: X(LDX,M) – **real** array *Input*
On entry: $X(i,j)$ must contain the i th observation for the j th independent variable, for $i = 1, 2, \dots, n$; $j = 1, 2, \dots, m$.
- 5: LDX – INTEGER *Input*
On entry: the first dimension of the array X as declared in the (sub)program from which G02DAF is called.
Constraint: $LDX \geq N$.
- 6: M – INTEGER *Input*
On entry: the total number of independent variables in the data set, m .
Constraint: $M \geq 1$.
- 7: ISX(M) – INTEGER array *Input*
On entry: indicates which independent variables are to be included in the model.
 If $ISX(j) > 0$, then the variable contained in the j th column of X is included in the regression model.
Constraints:
 $ISX(j) \geq 0$, for $j = 1, 2, \dots, m$.
 If MEAN = 'M', then exactly IP – 1 values of ISX must be > 0 .
 If MEAN = 'Z', then exactly IP values of ISX must be > 0 .
- 8: IP – INTEGER *Input*
On entry: the number of independent variables in the model, including the mean or intercept if present.
Constraint: $1 \leq IP \leq N$.
- 9: Y(N) – **real** array *Input*
On entry: observations on the dependent variable, y .
- 10: WT(*) – **real** array *Input*
On entry: if WEIGHT = 'W', then WT must contain the weights to be used in the weighted regression.
 If $WT(i) = 0.0$, then the i th observation is not included in the model, in which case the effective number of observations is the number of observations with non-zero weights. The values of RES and H will be set to zero for observations with zero weights.
 If WEIGHT = 'U', then WT is not referenced and the effective number of observations is n .
Constraint: if WEIGHT = 'W', $WT(i) \geq 0.0$, for $i = 1, 2, \dots, n$.
- 11: RSS – **real** *Output*
On exit: the residual sum of squares for the regression.

- 12: IDF – INTEGER *Output*
On exit: the degrees of freedom associated with the residual sum of squares.
- 13: B(IP) – *real* array *Output*
On exit: B(*i*), $i = 1, 2, \dots, IP$ contains the least-squares estimates of the parameters of the regression model, $\hat{\beta}$.
 If MEAN = 'M', then B(1) will contain the estimate of the mean parameter and B($i + 1$) will contain the coefficient of the variable contained in column j of X, where ISX(j) is the i th positive value in the array ISX.
 If MEAN = 'Z', then B(i) will contain the coefficient of the variable contained in column j of X, where ISX(j) is the i th positive value in the array ISX.
- 14: SE(IP) – *real* array *Output*
On exit: SE(i), $i = 1, 2, \dots, IP$ contains the standard errors of the IP parameter estimates given in B.
- 15: COV(IP*(IP+1)/2) – *real* array *Output*
On exit: the first $IP \times (IP + 1)/2$ elements of COV contain the upper triangular part of the variance-covariance matrix of the IP parameter estimates given in B. They are stored packed by column, i.e., the covariance between the parameter estimate given in B(i) and the parameter estimate given in B(j), $j \geq i$, is stored in COV($j \times (j - 1)/2 + i$).
- 16: RES(N) – *real* array *Output*
On exit: the (weighted) residuals, r_i , for $i = 1, 2, \dots, n$.
- 17: H(N) – *real* array *Output*
On exit: the diagonal elements of H, h_i , for $i = 1, 2, \dots, n$.
- 18: Q(LDQ,IP+1) – *real* array *Output*
On exit: the results of the QR decomposition:
 the first column of Q contains c ;
 the upper triangular part of columns 2 to IP + 1 contain the R matrix;
 the strictly lower triangular part of columns 2 to IP + 1 contain details of the Q matrix.
- 19: LDQ – INTEGER *Input*
On entry: the first dimension of the array Q as declared in the (sub)program from which G02DAF is called.
Constraint: LDQ \geq N.
- 20: SVD – LOGICAL *Output*
On exit: if a singular value decomposition has been performed then SVD will be .TRUE., otherwise SVD will be .FALSE..
- 21: IRANK – INTEGER *Output*
On exit: the rank of the independent variables.
 If SVD = .FALSE., then IRANK = IP.
 If SVD = .TRUE., then IRANK is an estimate of the rank of the independent variables.
 IRANK is calculated as the number of singular values greater than TOL \times (largest singular value). It is possible for the SVD to be carried out but IRANK to be returned as IP.

- 22: $P(2*IP+IP*IP)$ – *real* array *Output*
On exit: details of the QR decomposition and SVD if used.
 If $SVD = .FALSE.$, only the first IP elements of P are used these will contain the zeta values for the QR decomposition (see F08AEF (SGEQRF/DGEQRF) for details).
 If $SVD = .TRUE.$, the first IP elements of P will contain the zeta values for the QR decomposition (see F08AEF (SGEQRF/DGEQRF) for details) and the next IP elements of P contain singular values. The following IP by IP elements contain the matrix P^* stored by columns.
- 23: TOL – *real* *Input*
On entry: the value of TOL is used to decide if the independent variables are of full rank and if not what is the rank of the independent variables. The smaller the value of TOL the stricter the criterion for selecting the singular value decomposition. If $TOL = 0.0$, then the singular value decomposition will never be used; this may cause run time errors or inaccurate results if the independent variables are not of full rank.
Suggested value: $TOL = 0.000001$.
Constraint: $TOL \geq 0.0$.
- 24: $WK(5*(IP-1)+IP*IP)$ – *real* array *Output*
On exit: if on exit $SVD = .TRUE.$, then WK contains information which is needed by G02DGF; otherwise WK is used as workspace.
- 25: IFAIL – INTEGER *Input/Output*
On entry: IFAIL must be set to 0, -1 or 1. Users who are unfamiliar with this parameter should refer to Chapter P01 for details.
On exit: $IFAIL = 0$ unless the routine detects an error (see Section 6).
 For environments where it might be inappropriate to halt program execution when an error is detected, the value -1 or 1 is recommended. If the output of error messages is undesirable, then the value 1 is recommended. Otherwise, for users not familiar with this parameter the recommended value is 0. **When the value -1 or 1 is used it is essential to test the value of IFAIL on exit.**

6 Error Indicators and Warnings

If on entry $IFAIL = 0$ or -1 , explanatory error messages are output on the current error message unit (as defined by X04AAF).

Errors or warnings detected by the routine:

$IFAIL = 1$

On entry, $N < 2$,
 or $M < 1$,
 or $LDX < N$,
 or $LDQ < N$,
 or $TOL < 0.0$,
 or $IP \leq 0$,
 or $IP > N$.

$IFAIL = 2$

On entry, $MEAN \neq 'M'$ or $'Z'$,
 or $WEIGHT \neq 'W'$ or $'U'$.

$IFAIL = 3$

On entry, $WEIGHT = 'W'$ or $'V'$ and a value of $WT < 0.0$.

IFAIL = 4

On entry, a value of ISX < 0,
or the value of IP is incompatible with the values of MEAN and ISX,
or IP is greater than the effective number of observations.

IFAIL = 5

The degrees of freedom for the residuals are zero, i.e., the designated number of parameters is equal to the effective number of observations. In this case the parameter estimates will be returned along with the diagonal elements of H , but neither standard errors nor the variance-covariance matrix will be calculated.

IFAIL = 6

The singular value decomposition has failed to converge, see F02WUF. This is an unlikely error.

7 Accuracy

The accuracy of this routine is closely related to the accuracy of F08AEF (SGEQRF/DGEQRF) and F02WUF. These routine documents should be consulted.

8 Further Comments

Standardised residuals and further measures of influence can be computed using G02FAF. This routine requires, in particular, the results stored in RES and H.

9 Example

Data from an experiment with four treatments and three observations per treatment are read in. The treatments are represented by dummy (0 – 1) variables. An unweighted model is fitted with a mean included in the model.

9.1 Program Text

Note: the listing of the example program presented below uses *bold italicised* terms to denote precision-dependent details. Please read the Users' Note for your implementation to check the interpretation of these terms. As explained in the Essential Introduction to this manual, the results produced may not be identical for all implementations.

```
*      G02DAF Example Program Text
*      Mark 14 Release.  NAG Copyright 1989.
*      .. Parameters ..
      INTEGER          MMAX, NMAX
      PARAMETER       (MMAX=5,NMAX=12)
      INTEGER          NIN, NOUT
      PARAMETER       (NIN=5,NOUT=6)
*      .. Local Scalars ..
      real            RSS, TOL
      INTEGER          I, IDF, IFAIL, IP, IRANK, J, M, N
      LOGICAL          SVD
      CHARACTER        MEAN, WEIGHT
*      .. Local Arrays ..
      real            B(MMAX), COV((MMAX*MMAX+MMAX)/2), H(NMAX),
+                   P(MMAX*(MMAX+2)), Q(NMAX,MMAX+1), RES(NMAX),
+                   SE(MMAX), WK(MMAX*MMAX+5*(MMAX-1)), WT(NMAX),
+                   X(NMAX,MMAX), Y(NMAX)
      INTEGER          ISX(MMAX)
*      .. External Subroutines ..
      EXTERNAL         GO2DAF
*      .. Executable Statements ..
      WRITE (NOUT,*) 'G02DAF Example Program Results'
*      Skip heading in data file
      READ (NIN,*)
      READ (NIN,*) N, M, WEIGHT, MEAN
      WRITE (NOUT,*)
```

```

      IF (N.LE.NMAX .AND. M.LT.MMAX) THEN
      IF (WEIGHT.EQ.'W' .OR. WEIGHT.EQ.'w') THEN
      DO 20 I = 1, N
      READ (NIN,*) (X(I,J),J=1,M), Y(I), WT(I)
20    CONTINUE
      ELSE
      DO 40 I = 1, N
      READ (NIN,*) (X(I,J),J=1,M), Y(I)
40    CONTINUE
      END IF
      READ (NIN,*) (ISX(J),J=1,M)
*     Calculate IP
      IP = 0
      IF (MEAN.EQ.'M' .OR. MEAN.EQ.'m') IP = IP + 1
      DO 60 I = 1, M
      IF (ISX(I).GT.0) IP = IP + 1
60    CONTINUE
*     Set tolerance
      TOL = 0.00001e0
      IFAIL = 0
*
      CALL G02DAF(MEAN,WEIGHT,N,X,NMAX,M,ISX,IP,Y,WT,RSS,IDF,B,SE,
+              COV,RES,H,Q,NMAX,SVD,IRANK,P,TOL,WK,IFAIL)
*
      IF (SVD) THEN
      WRITE (NOUT,99999) 'Model not of full rank, rank = ', IRANK
      WRITE (NOUT,*)
      END IF
      WRITE (NOUT,99998) 'Residual sum of squares = ', RSS
      WRITE (NOUT,99999) 'Degrees of freedom = ', IDF
      WRITE (NOUT,*)
      WRITE (NOUT,*) 'Variable   Parameter estimate   Standard error'
      WRITE (NOUT,*)
      DO 80 J = 1, IP
      WRITE (NOUT,99997) J, B(J), SE(J)
80    CONTINUE
      WRITE (NOUT,*)
      WRITE (NOUT,*) '   Obs           Residuals           H'
      WRITE (NOUT,*)
      DO 100 I = 1, N
      WRITE (NOUT,99997) I, RES(I), H(I)
100   CONTINUE
      END IF
      STOP
*
99999 FORMAT (1X,A,I4)
99998 FORMAT (1X,A,e12.4)
99997 FORMAT (1X,I6,2e20.4)
      END

```

9.2 Program Data

G02DAF Example Program Data

```

12 4 'U' 'M'
1.0 0.0 0.0 0.0 33.63
0.0 0.0 0.0 1.0 39.62
0.0 1.0 0.0 0.0 38.18
0.0 0.0 1.0 0.0 41.46
0.0 0.0 0.0 1.0 38.02
0.0 1.0 0.0 0.0 35.83
0.0 0.0 0.0 1.0 35.99
1.0 0.0 0.0 0.0 36.58
0.0 0.0 1.0 0.0 42.92
1.0 0.0 0.0 0.0 37.80
0.0 0.0 1.0 0.0 40.43
0.0 1.0 0.0 0.0 37.89
1 1 1 1

```

9.3 Program Results

G02DAF Example Program Results

Model not of full rank, rank = 4

Residual sum of squares = 0.2223E+02

Degrees of freedom = 8

Variable	Parameter estimate	Standard error
1	0.3056E+02	0.3849E+00
2	0.5447E+01	0.8390E+00
3	0.6743E+01	0.8390E+00
4	0.1105E+02	0.8390E+00
5	0.7320E+01	0.8390E+00

Obs	Residuals	H
1	-0.2373E+01	0.3333E+00
2	0.1743E+01	0.3333E+00
3	0.8800E+00	0.3333E+00
4	-0.1433E+00	0.3333E+00
5	0.1433E+00	0.3333E+00
6	-0.1470E+01	0.3333E+00
7	-0.1887E+01	0.3333E+00
8	0.5767E+00	0.3333E+00
9	0.1317E+01	0.3333E+00
10	0.1797E+01	0.3333E+00
11	-0.1173E+01	0.3333E+00
12	0.5900E+00	0.3333E+00
